

# Tests and model choice : asymptotics

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# Outline

- 1 Bayesian testing : the Bayes factor
  - Bayes factor
  - Consistency of the Bayes factor or of the model selection :
- 2 Non parametric tests
  - Parametric vs Nonparametric
  - Construction of nonparametric priors
  - A special case : Point null hypothesis
  - Parametric null hypothesis
- 3 General conditions for consistency of  $B_{1/2}$  in non iid case for GOF types
- 4 Nonparametric/Nonparametric case
- 5 Conclusion

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# Bayes factor

▶ **Model**  $X \sim f(\cdot|\theta)$ ,  $\theta \in \Theta$ ;  $\theta \sim \Pi$

▶ **Testing problem**

$H_0 : \theta \in \Theta_0$ ,  $H_1 : \theta \in \Theta_1$ ,  $\Theta_0 \cap \Theta_1 = \emptyset$  ( or  $\Pi[\Theta_0 \cap \Theta_1] = 0$ )

▶ **0-1 loss function** Bayes estimate :

$$\delta^\pi = 1 \quad \text{iff } \Pi[\Theta_1|X] > \Pi[\Theta_0|X]$$

↓ **Posterior odds ratio**

$$\frac{\Pi[\Theta_0|X]}{\Pi[\Theta_1|X]} = \frac{\int_{\Theta_0} f(X|\theta) d\Pi_0(\theta)}{\underbrace{\int_{\Theta_1} f(X|\theta) d\Pi_1(\theta)}_{\frac{m_0(X)}{m_1(X)}}} \times \frac{\pi[\Theta_0]}{\pi[\Theta_1]}$$

$$BF_{0/1} := \frac{m_0(X)}{m_1(X)}, \quad d\Pi_j(\theta) = \mathbb{1}_{\Theta_j} \frac{d\Pi(\theta)}{\Pi(\Theta_j)}$$

if  $BF_{0/1}$  large  $\rightarrow H_0$

else  $\rightarrow H_1$

# Model choice

- ▶ **Multiple models**  $\mathfrak{M}_j : f_{j,\theta_j}, \theta_j \in \Theta_j$
- ▶ **Hierarchical Prior**

$$d\Pi(j, \theta_j) = \Pi(j) d\Pi_j(\theta_j)$$

- ▶ **Posterior**

$$d\Pi(j, \theta_j | X) \propto \Pi(j) d\Pi_j(\theta_j) f_{j,\theta_j}(X), \quad d\Pi(j | X) \propto \Pi(j) \underbrace{\int_{\Theta_j} f_{j,\theta_j}(X) d\Pi_j(\theta_j)}_{m_j(X)}$$

- ▶ **0-1 loss function** Bayes estimate

$$\delta^\pi(X) = \operatorname{argmax}\{\Pi(\mathfrak{M}_j | X) \propto m_j(X) \times \Pi(\mathfrak{M}_j), j \in \mathcal{J}\}$$

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# Consistency of the Bayes factor $BF_{0/1} = \frac{m_0(X)}{m_1(X)}$

**Definition 1** The Bayes factor is said *consistent* IFF

$$BF_{0/1} \rightarrow +\infty, \quad \text{in proba when } X \sim f_\theta \in \mathcal{H}_0$$

$$BF_{0/1} \rightarrow 0, \quad \text{in proba when } X \sim f_\theta \in \mathcal{H}_1$$

**Interpretation :** As  $n$  goes to infinity you are bound to make the correct decision

# Consistency of the model selection

▶ **true model** True parameter  $\theta^* \in \cup_j \Theta_j$

$$\mathfrak{M}^* = \min\{\Theta_j; \theta^* \in \Theta_j\}, \quad \Theta_j \leq \Theta_{j'} \Leftrightarrow \Theta_j \subset \Theta_{j'}$$

e.g. Mixtures, Variable selections, graph selection etc. . .

▶ **Consistency**  $\delta^\pi$  is consistent iff

$$P_{\theta^*}(\delta^\pi \neq \mathfrak{M}^*) \rightarrow 0$$

*Whether BF or model selection procedure : based on the asymptotic behaviour of the marginal likelihoods  $m_j(X)$*



# BIC approximation of the marginal likelihood

- **Bayes factor : marginal likelihood ratio** : acts like a penalized likelihood ratio

**BIC approximation** in **finite dim & regular** models

$$\overline{X} = X^n = (X_1, \dots, X_n)$$

$$\log m_j(X^n) = \log f(X^n | \hat{\theta}_j) - \frac{d_j}{2} \log n + O_p(1)$$
$$d_j = \dim(\Theta_j), \quad \hat{\theta}_j = \text{MLE under } \Theta_j.$$

→ Different penalization if **non regular or infinite dim**

# How does BIC work ?

$$\ell_n(\theta; \mathfrak{M}) = \log f(X^n | \theta; \mathfrak{M}).$$

$$m_j(X^n) = e^{\ell_n(\hat{\theta}_j; \mathfrak{M}_j)} \int_{\Theta_j} e^{\ell_n(\theta; \mathfrak{M}_j) - \ell_n(\hat{\theta}_j; \mathfrak{M}_j)} \pi_j(\theta) d\theta, \quad \hat{\theta}_j = \text{mle in } \Theta_j$$

## ► Local asymptotic normality+ consistency

$$\ell_n(\theta) - \ell_n(\hat{\theta}_j) = \frac{-n(\theta - \hat{\theta}_j)^t I(\hat{\theta}_j)(\theta - \hat{\theta}_j)}{2} (1 + o_p(1))$$

$$\Pi_j(\|\theta - \hat{\theta}_j\| > \epsilon | X^n) = o_p(1)$$

## ► positive, continuous and finite prior density

$$0 < \inf_{\|\theta - \hat{\theta}_j\| < \epsilon} \pi_j(\theta) \leq \sup_{\|\theta - \hat{\theta}_j\| < \epsilon} \pi_j(\theta) < +\infty$$

# Extension to irregular models : a more general approach

True parameter  $\theta^*$ ,  $\Theta_j \subset \mathbb{R}^{d_j}$ ,

$$m_j(X^n) = e^{\ell_n(\theta_j^*)} \int_{\Theta_j} e^{\ell_n(\theta) - \ell_n(\theta_j^*)} \pi_j(\theta) d\theta, \quad \theta_j^* = \text{KL - projtn onto } \Theta_j$$

## ► Deterministic approximation

$$\ell_n(\theta) - \ell_n(\theta_j^*) \approx -nH(\theta_j^*, \theta), \quad H(\theta_j^*, \theta) = \frac{E_{\theta^*} \left( \ell_n(\theta_j^*) - \ell_n(\theta) \right)}{n}$$

$$\log m_j(X^n) = \underbrace{\ell_n(\theta_j^*)}_{\text{model bias}} + \underbrace{\log \Pi_j(H(\theta_j^*, \theta) \lesssim 1/n)}_{\text{prior penalty}} + o_p(\log n)$$

# Understanding the prior penalty $\Pi_j(H(\theta_j^*, \theta) \lesssim 1/n)$

## ▶ Regular models

$$H(\theta_j^*, \theta) = \frac{(\theta - \theta_j^*)^t I(\theta_j^*) (\theta - \theta_j^*)}{2} (1 + o(1)) \Rightarrow$$

$$\Pi_j(H(\theta_j^*, \theta) \lesssim 1/n) \approx \pi_j(\theta_j^*) (C/n)^{d_j/2} \Rightarrow -\frac{d_j}{2} \log n + O_p(1)$$

## ▶ Irregular models

$$H(\theta_j^*, \theta) \neq \frac{(\theta - \theta_j^*)^t I(\theta_j^*) (\theta - \theta_j^*)}{2} (1 + o(1))$$

[We need to understand the geometry associated to  $H(\theta_j^*, \theta)$ .]

## Example of mixture models : overspecified case

$$f_{\theta}(x) = \sum_{j=1}^k p_j g_{\gamma_j}(x), \quad \gamma_j \in \Gamma, \quad \sum_{j=1}^k p_j = 1$$

► If true distribution

$$f_{\theta^*}(x) = \sum_{j=1}^{k^*} p_j^* g_{\gamma_j^*}(x), \quad k^* < k$$

[Then the model is non identifiable]

$k = 2$  and  $k^* = 1$

$$f_{\theta}(x) = p_1 g_{\gamma_1} + (1 - p_1) g_{\gamma_2}, \quad f^*(x) = g_{\gamma^*}$$

Then  $f_{\theta} = f_{\theta^*}$  IFF

$$p_1 = 1, \quad \gamma_1 = \gamma^* \quad \text{or} \quad \gamma_1 = \gamma_2 = \gamma^*$$

$\Theta^* = \{\theta : f_{\theta} = f_{\theta^*}\} \neq \{\theta^*\}$  even up to a permutation

Understanding  $H(\theta_j^*, \theta)$  in mixtures  $f_{\theta^*}(x) = \sum_{j=1}^{k^*} p_j^* g_{\gamma_j^*}(x)$ ,  $\mathfrak{M}_k = \{f_\theta(x) = \sum_{j=1}^k p_j g_{\gamma_j}(x), \gamma_j \in \Gamma\}$

$$k^* < k \quad \& \quad \theta_{k^*}^* = \theta^* \quad H(\theta^*, \theta)$$

► varies with the configuration  $\mathbf{t} = (t_1, \dots, t_{k^*}, t_{k^*+1})$   
 $\mathbf{t} = (t_j, j \leq k^* + 1)$  is the partition of  $\{1, \dots, k\}$

$$t_j = \{\ell; \|\gamma_\ell - \gamma_j^*\| \leq \epsilon\}, \quad j \leq k^*; \quad t_{k^*+1} = \{\ell; \min_{j \leq k^*} \|\theta_\ell - \theta_j^*\| > \epsilon\}$$

On  $\mathbf{t}$ ;  $p(j) = \sum_{\ell \in t_j} p_\ell$ ,  $q_\ell = p_\ell / p(j)$  if  $\ell \in t_j$

$$\begin{aligned} \sqrt{H(\theta^*, \theta)} &\asymp \sum_{j=1}^{k^*} \left[ \left\| \sum_{\ell \in t_j} q_\ell \gamma_\ell - \gamma_j^* \right\| + |p(j) - p_j^*| + \sum_{\ell \in t_j} \frac{p_\ell}{p(j)} \|\gamma_\ell - \gamma_j^*\|^2 \right] \\ &+ \sum_{\ell \in t_{k^*+1}} p_\ell \end{aligned}$$

$$\Pi_k(H(\theta^*, \theta) \lesssim 1/n)$$

► **prior**

$$(p_1, \dots, p_k) \sim \mathcal{D}(\alpha, \dots, \alpha), \quad \gamma_j \stackrel{iid}{\sim} \pi_\gamma$$

► **If  $\alpha < d/2$**

$$\Pi_k(H(\theta^*, \theta) \lesssim 1/n) \approx n^{-(k^*d + k^* - 1 + (k - k^*)\alpha)/2}$$

[ (prior) sparsest configuration : emptying the extra states]

► **If  $\alpha > d/2$**

$$\Pi_k(H(\theta^*, \theta) \lesssim 1/n) \approx n^{-(k^*d + k^* - 1 + (k - k^*)d/2)/2}$$

[ (prior) sparsest configuration : merging the extra states]

Prior penalty  $D < \dim(\Theta_k)$

# Impact on consistency

$$BF_{k/k+1} = \frac{\int_{\Theta_k} f_{\theta}(X^n) \pi_k(\theta) d\theta}{\int_{\Theta_{k+1}} f_{\theta}(X^n) \pi_{k+1}(\theta) d\theta}$$

► If  $\theta^* \in \Theta_{k+1} \setminus \Theta_k$  (Regular models)

$$\log m_k(X^n) = \ell_n(\theta_k^*) - \ell_n(\theta^*) + O_p(\log n) \approx -nKL(\theta^*, \theta_k^*) \rightarrow -\infty$$

► If  $\theta^* \in \Theta_k \subset \Theta_{k+1}$  irregular model

$$D^* = \dim(\Theta_k) + \alpha, \quad \text{if } \alpha < d/2 \quad \& \quad D^* = \dim(\Theta_k) + d/2 \text{ if } \alpha > d/2$$

Then

$$\log BF_{k/k+1} = -\frac{\dim(\Theta_k) - D^*}{2} \log n + o_p(\log n) \rightarrow +\infty$$



# Nonparametric cases : At least one of the models is NP

## ► Case 1 : Parametric vs Non parametric :

$$\mathfrak{M}_0 : \theta_0 \in \Theta \subset \mathbb{R}^d, \quad \mathfrak{M}_1 : \theta_1 \in \Theta_1, \quad \dim(\Theta_1) = +\infty$$

e.g. Goodness of fit tests ; testing for linearity in regression etc .

...

## ► Case 2 : Nonparametric vs Nonparametric

$$\mathfrak{M}_0 : \theta_0 \in \Theta_0, \quad \mathfrak{M}_1 : \theta_1 \in \Theta_1, \quad \dim(\Theta_1), \dim(\Theta_0) = +\infty$$

e.g. Testing for monotonicity, independence, two sample tests etc. . .

## ► Case 3 : High dimensional model selection

$$\mathfrak{M}_k : \theta \in \Theta_k \subset \mathbb{R}^{d_k}, \quad k \in \mathcal{K}, \quad \text{card}(\mathcal{K}) \text{ large}$$

e.g. regression models (variable selection)

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# Parametric vs NP

$$X^n = (X_1, \dots, X_n) \sim f_\theta^n,$$

► **Test problem** :  $\Theta_0 \subset \mathbb{R}^d$ ,  $\dim(\Theta_1) = +\infty$

$$H_0 : f_\theta^n \in \mathcal{F}_0 = \{f_\theta^n, \theta \in \Theta_0\}, \quad H_1 : f_\theta^n \in \mathcal{F}_1 = \{f_\theta^n, \theta \in \Theta_1\}$$

Examples :

- Goodness of fit in iid cases :  $X_i \stackrel{iid}{\sim} f$ ,

$$\mathcal{F}_0 = \{f_\theta, \theta \in \Theta_0\}, \quad \mathcal{F}_1 = \mathcal{F}_0^c.$$

- Linear/partially linear

$$y_i = \alpha + \beta^t \mathbf{w}_i + f(x_i) + \epsilon_i, \epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

$$H_0 : f = 0, \quad H_1 : f \neq 0$$

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# Non parametric priors on $\mathcal{F}_1$

$$H_0 : f \in \mathcal{F}_0 = \{f_\theta, \theta \in \Theta\}, \quad H_1 : f \in \mathcal{F}_1 \quad \Theta \subset \mathbb{R}^d$$

- ▶ **Parameter space**  $\mathcal{F} = \mathcal{F}_0 \cup \mathcal{F}_1$
- ▶ **Non parametric prior  $\pi_1$  on  $\mathcal{F}_1$**  Prior on  $H_1$ 
  - Your favourite nonparametric prior *e.g. Gaussian processes, Levy processes, Mixtures*
  - Check that  $\Pi_1[\mathcal{F}_0] = 0$ , e.g.

$$\mathcal{F}_0 = \{\mathcal{N}(\mu, \sigma^2), (\mu, \sigma) \in \mathbb{R} \times \mathbb{R}^+\}, \quad \Pi_1 : \sum_{j=1}^k p_j \mathcal{N}(\mu_j, \sigma_j^2), \quad k > 1$$

- Should we care for more ? **Yes : consistency**

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# Case of point null hypothesis (case of iid observations)

$$H_0 : f = f_0, \quad H_1 : f \neq f_0$$

► **Prior on**  $\mathcal{F}_1 = \mathcal{F} - \{f_0\}$

- Corresponds to a prior on  $\mathcal{F}$

$$\Pi(f) = p_0 \delta_{(f_0)} + (1-p_0) \Pi_1(f), \quad \Pi_1 = \text{proba on } \mathcal{F} \quad \Pi_1(\{f_0\}) = 0$$

- Dass & Lee :
  - $BF_{0/1}$  **always consistent** under  $f_0$ .
  - if  $d\Pi_1(\cdot|X^n)$  is consistent at  $f \in \mathcal{F} - \{f_0\}$ , then the  $BF_{0,1}$  is consistent under  $f$ .

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## Remark on Dass & Lee

► **Convergence under  $f_0$**

Comes from **Doob theorem** because  $\Pi[\{f_0\}] = p_0 > 0$

$$\Pi(f) = p_0 \delta_{(f_0)} + (1 - p_0) \Pi_1(f)$$

► **Harder to detect  $H_0$  than  $H_1$  :**

$f_0 \in \mathcal{F}$ ,  $\rightarrow$  can be approximated under  $\mathcal{F}_1$

$\Downarrow$  typically

$$H_1 : BF_{0/1} \lesssim e^{-nc(f)} \quad H_0 : BF_{0/1} \lesssim n^{-q_0}$$

# On posterior concentration

- **Posterior concentration**  $\epsilon_n = o(1)$  Prove that

$$E_{\theta^*} [\mathbb{P}(d(\theta, \theta^*) > M\epsilon_n | Y^n)] = o(1), \quad \ell_n(\theta) = \log f_\theta(Y^n)$$

- **Conditions**

1 **KL condition**

$$\pi \left[ KL_n(\theta^*, \theta) \leq n\epsilon_n^2, V_n(\theta^*, \theta) \leq \kappa n\epsilon_n^2 \right] \gtrsim e^{-nc\epsilon_n^2}$$

$$KL_n(\theta^*, \theta) = E_{\theta^*}(\ell_n(\theta^*) - \ell_n(\theta)), \quad V_n(\theta^*, \theta) = V_{\theta^*}(\ell_n(\theta^*) - \ell_n(\theta))$$

- 2 **Testing condition**  $\exists \Theta_n \subset \Theta : \pi(\Theta_n^c) \leq e^{-n(c+2)\epsilon_n^2}$  and  $\phi_n \in [0, 1]$

$$E_{\theta^*}(\phi_n) = o(1), \quad \sup_{d(\theta^*, \theta) > M\epsilon_n, \theta \in \Theta_n} E_\theta(1 - \phi_n) \leq e^{-n(c+2)\epsilon_n^2}$$

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# Proof

$$\Pi(d(\theta, \theta^*) > \epsilon_n | Y^n) = \frac{\int_{B_n} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta)}{\int_{\Theta} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta)} := \frac{N_n}{D_n}$$

$$\begin{aligned} E_{\theta^*} [\Pi(d(\theta, \theta^*) > \epsilon_n | Y^n)] &= E_{\theta^*} \left[ \phi_n \times \frac{N_n}{D_n} \right] + E_{\theta^*} \left[ (1 - \phi_n) \times \frac{N_n}{D_n} \right] \\ &\leq E_{\theta^*} [\phi_n] + P_{\theta^*} \left[ D_n < e^{-n(c+3/2)\epsilon_n^2} \right] + e^{n(c+3/2)\epsilon_n^2} E_{\theta^*} (N_n(1 - \phi_n)) \\ &= E_{\theta^*} [\phi_n] + P_{\theta^*} \left[ D_n < e^{-n(c+3/2)\epsilon_n^2} \right] + e^{n(c+3/2)\epsilon_n^2} \int_{B_n} E_{\theta} (1 - \phi_n) d\pi(\theta) \\ &= o(1) + P_{\theta^*} \left[ D_n < e^{-n(c+2)\epsilon_n^2} \right] + e^{n(c+3/2)\epsilon_n^2} \left( e^{-n(c+2)\epsilon_n^2} + \Pi(\Theta_n^c) \right) \\ &= o(1) + P_{\theta^*} \left[ D_n < e^{-n(c+2)\epsilon_n^2} \right] \end{aligned}$$

# Control of $P_{\theta^*} \left[ D_n < e^{-n(c+2)\epsilon_n^2} \right]$ : KL condition

$$\begin{aligned} D_n &= \int_{\Theta} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta) \geq \int_{S_n} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta) \\ &\geq \int_{S_n} \mathbb{I}_{\ell_n(\theta) - \ell_n(\theta^*) > -3/2n\epsilon_n^2} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta) \\ &\geq e^{-3/2n\epsilon_n^2} \pi(S_n \cap \{\ell_n(\theta) - \ell_n(\theta^*) > -3/2n\epsilon_n^2\}) \\ &= e^{-3/2n\epsilon_n^2} \left( \pi(S_n) - \pi(S_n \cap \{\ell_n(\theta) - \ell_n(\theta^*) \leq -3/2n\epsilon_n^2\}) \right) \end{aligned}$$

and

$$\begin{aligned} P_{\theta^*} \left( \pi(S_n \cap \{\ell_n(\theta) - \ell_n(\theta^*) \leq -3/2n\epsilon_n^2\}) > \pi(S_n)/2 \right) \\ \leq \frac{2}{\pi(S_n)} \int_{S_n} \underbrace{P_{\theta^*} \left( \ell_n(\theta) - \ell_n(\theta^*) \leq -3/2n\epsilon_n^2 \right)}_{\text{KL condition: } \lesssim \frac{1}{n\epsilon_n^2}} d\pi(\theta) \lesssim \frac{1}{n\epsilon_n^2} \end{aligned}$$



# What are these tests ?

▶ **The tests  $\phi_n$  depend on the metric  $d(\theta, \theta')$**

● ▶ **Case of iid data with weak topology**

$$U = \{f; |\int \varphi_j f(x) dx - \int \varphi_j f_0(x) dx| \leq \epsilon, \quad j = 1, \dots, J\} :$$

Tests always exist

● ▶  $L_1$  metric :  $d(f, f') = \int |f(x) - f'(x)| dx$

$$\phi_n = \max \phi_{n, f_\ell}, \quad \phi_{n, f_\ell} = \mathbb{I}_{\sum_{i=1}^n [\mathbb{I}_{y_i \in A(f_\ell, f_0)} - P_{f_0}(A(f_\ell, f_0))] > n\delta \|f_\ell - f_0\|_1}$$

with

$$A(f_\ell, f_0) = \{y; f_\ell(y) > f_0(y)\}$$

[existence of tests  $\leftrightarrow$  Bound on the  $L_1$  covering number  $N(\cdot) \leq e^{nc\epsilon_n^2}$ ]

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# Summary of the first day : $BF_{0/1} = \frac{m_0(Y^n)}{m_1(Y^n)}$

## ► Parametric

$$\log m_j(Y^n) = \ell_n(\theta_j^*) - \underbrace{\frac{D_j}{2} \log n}_{\log \pi_j(d(\theta_j^*, \theta) \leq 1/n)} + o_p(\log n)$$

- Regular model  $D_j = \dim(\Theta_j)$
- Irregular model  $D_j = D_j(\theta^*) \neq \dim(\Theta_j)$
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## Summary 2 : towards nonparametric

### ► Posterior concentration rates

$$\pi(B_n | Y^n) = \frac{\int_{B_n} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta)}{\int_{\Theta} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi(\theta)} := \frac{N_n}{D_n}$$

- Lower bound on  $D_n$  :  $P_{\theta^*}[D_n > e^{-n\epsilon_n^2(c+3/2)}] = 1 + o(1)$  If

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# Outline

- 1 Bayesian testing : the Bayes factor
  - Bayes factor
  - Consistency of the Bayes factor or of the model selection :
- 2 **Non parametric tests**
  - Parametric vs Nonparametric
  - Construction of nonparametric priors
  - A special case : Point null hypothesis
  - **Parametric null hypothesis**
- 3 General conditions for consistency of  $B_{1/2}$  in non iid case for GOF types
- 4 Nonparametric/Nonparametric case
- 5 Conclusion

# General result under non i.i.d observations : sufficient conditions

## ► Context

• Under  $\mathfrak{M}_0$  :  $Y \sim f_{0,\theta_0}^n$ ,  $\theta_0 \in \Theta_0 \subset \mathbb{R}^d$

• Under  $\mathfrak{M}_1$  :  $Y \sim f_{1,\theta_1}^n$ ,  $\theta_1 \in \Theta_1$  (infinite dim)

$d_n(.,.)$  (semi) metric on the distributions (e.g. total variation, KL, etc.)

$$\liminf_n \inf_{\theta_0 \in \Theta_0} d_n(f_{1,\theta_1}, f_{0,\theta_0}) := d(\theta_1, \mathfrak{M}_0)$$

$$\liminf_n \inf_{\theta_1 \in \Theta_1} d_n(f_{0,\theta_0}, f_{1,\theta_1}) := d(\theta_0, \mathfrak{M}_1)$$

[ Typically  $\mathfrak{M}_0 \subset \mathfrak{M}_1$  ]

# Conditions under $\mathfrak{M}_1$ (bigger model) : $\theta^* = \theta_1$ — often easier

bound from above  $m_0(Y^n)$  and from below  $m_1(Y^n)$

$$m_j(Y^n) = \int_{\Theta_j} e^{\ell_n(j, \theta) - \ell_n(\theta^*)} d\pi_j(\theta)$$

$d(\theta^*, \mathfrak{M}_0) > 0$  (separated case)

► If

$$\forall \epsilon > 0, \quad P_{\theta^*} \left[ m_1(Y^n) < e^{-n\epsilon^2} \right] = o(1)$$

[Consistency under  $\mathfrak{M}_1$ ]

► If,  $\forall \epsilon > 0, \exists a > 0$  and tests  $\phi_n$  and  $\Theta_{0,n} \subset \Theta_0$  s.t.

$$E_{\theta^*} [\phi_n] = o(1), \quad \sup_{\theta_0 \in \Theta_{0,n}} E_{\theta_0} [1 - \phi_n] \leq e^{-an}, \quad \pi_0(\Theta_{0,n}^c) < e^{-n\epsilon}$$

[Statistical separation between  $\theta^*$  and  $\mathfrak{M}_0$ ]

Then  $B_{0/1} < e^{-an/2}$ , with proba going to 1 under  $P_{\theta^*}$

# Conditions under $\mathfrak{M}_0$ (smaller model) ; $\theta^* \in \mathfrak{M}_0 \subset \mathfrak{M}_1$

Case :  $d(\theta^*, \mathfrak{M}_1) = 0$ , &  $\Theta_0 \subset \mathbb{R}^d$

► **(parametric) If**  $\exists k_0 > 0$

$$n^{k_0/2} \pi_0 [\{\theta \in \Theta_0 : KL(f_{0,\theta^*}^n, f_{0,\theta}^n) \leq 1, \quad V(f_{0,\theta^*}^n, f_{0,\theta}^n) \leq 1\}] \geq C$$

for some positive constants  $C$ .

► **(NP)**  $f_{\theta^*} = f_{0,\theta^*}$  If  $\exists \epsilon_n \downarrow 0$  with

$A_{\epsilon_n}(\theta^*) = \{\theta \in \Theta_1 : d_n(f_{\theta^*}^n, f_{1,\theta}^n) < \epsilon_n\}$  such that

1.

$$P_{\theta^*}^n [\pi_1 [A_{\epsilon_n}^c(\theta^*) | Y]] = o(1)$$

2.

$$n^{k_0/2} \pi_1 [A_{\epsilon_n}(\theta^*)] = o(1).$$

Then  $B_{0/1} \rightarrow +\infty$  under  $P_{\theta^*}$

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# Application to Partial linear regressions

$$y_i = \alpha + \beta^t \mathbf{w}_i + f(x_i) + \epsilon_i, \epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

$$(\mathbf{w}_i, x_i) \sim G \text{ i.i.d.}, \quad E[\mathbf{w}] = 0, \quad E[\mathbf{w}\mathbf{w}^t] > 0$$

►  $\mathfrak{M}_0$  :  $(\alpha, \beta, f, \sigma)$  s.t.

$$H(f) := \inf_{(\alpha', \beta') \in \mathbb{R}^{d+1}} E \left[ (\alpha' + (\beta')^t \mathbf{w} - f(x))^2 \right] = 0$$

$$\Leftrightarrow y_i = \alpha_1 + \beta_1^t \mathbf{w}_i + \epsilon_i$$

►  $\mathfrak{M}_1$  :  $(\alpha, \beta, f, \sigma)$  s.t.

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- **prior** hierarchical (adaptive) Gaussian process prior on  $f$

$$f = \sum_{k=1}^K \tau_k Z_k \xi_k, \quad (\xi_k) = \text{BON}$$

$$K \sim P, \quad Z_k \sim \mathcal{N}(0, 1)$$

$$(\alpha, \beta, \sigma) \sim \pi_0$$

$$h_j(x) = E[w_j | X = x], \quad \mathbf{w} = (w_1, \dots, w_d)$$

- **If**  $\exists j$  s.t.  $\langle h_j, \xi_1 \rangle \neq 0$  then  $B_{0/1}$  is consistent under  $\mathfrak{M}_0$  like  $n^p$



# Nonparametric/Nonparametric testing problem

$$B_{0/1} = m_0(Y)/m_1(Y)$$

- ▶ Both  $\mathfrak{M}_0$  and  $\mathfrak{M}_1$  are non parametric &  $\mathfrak{M}_0 \subset \mathfrak{M}_1$
- ▶ **Lower bound** Not too hard but sharp ?

$$m_j(Y) \geq e^{-(c_j+2)n\epsilon_{n,j}^2}, \quad \pi_j(B_{KL}(\theta^*, n\epsilon_{n,j}^2)) \gtrsim e^{-nc_j\epsilon_n^2}$$

- ▶ **upper bound** Harder
  - Tests control : ok – tools for it

$$\int_{d(\theta^*, \theta) > \epsilon_{n,j}} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi_j(\theta) \lesssim e^{-c'_j n \epsilon_{n,j}^2}$$

- Control on  $\int_{d(\theta^*, \theta) \leq \epsilon_{n,j}} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi_j(\theta)$  : damn it

$$\text{If } d(\theta^*, \mathfrak{M}_j) = 0 \quad \begin{cases} E_{\theta^*}[N_{n,j}] := E_{\theta^*} \left[ \int_{d(\theta^*, \theta) \leq \epsilon_{n,j}} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi_j(\theta) \right] \\ \stackrel{\text{Fubini}}{=} \pi_j(d(\theta^*, \theta) \leq \epsilon_{n,j}) \lesssim e^{-c'_j n \epsilon_{n,j}^2} \end{cases}$$

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$$\text{If } d(\theta^*, \mathfrak{M}_j) = 0 \quad \left\{ \begin{array}{l} E_{\theta^*}[N_{n,j}] := E_{\theta^*} \left[ \int_{d(\theta^*, \theta) \leq \epsilon_{n,j}} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi_j(\theta) \right] \\ \stackrel{\text{Fubini}}{=} \pi_j(d(\theta^*, \theta) \leq \epsilon_{n,j}) \stackrel{?}{\lesssim} e^{-c'_j n \epsilon_{n,j}^2} \end{array} \right.$$

- ▶ **Multiple models**  $\Theta_\lambda, \lambda \in \Lambda$  (possibly continuous) **Aim**

$$\hat{\lambda} = \operatorname{argmax}\{\pi(\lambda|Y^n), \lambda \in \Lambda\} \quad \pi(\lambda|Y^n) \propto \pi(\lambda)m_\lambda(Y^n)$$

- ▶ **What is  $\lambda^*$  ? Two contexts**

- *Almost finite case* :  $\Lambda \subset \mathbb{N}, \Theta_\lambda \subset \Theta_{\lambda+1}$  and

$$\exists \lambda_0 \text{ s.t. } \theta^* \in \Theta_{\lambda_0}, \quad \lambda^* = \min\{\lambda; \theta^* \in \Theta_\lambda\}$$

[Sharp tools like BIC]

- *Boundary case*  $\theta^* \in \mathcal{Cl}(\cup_\lambda \Theta_\lambda)$  but  $\forall \lambda, \theta^* \notin \Theta_\lambda$

Claim :  $\lambda^* = \text{Oracle}$

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- ▶ **Multiple models**  $\Theta_\lambda, \lambda \in \Lambda$  (possibly continuous) Aim

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# Where does the oracle come from ?

$$\begin{aligned} m_\lambda(Y^n) &= \int_{\Theta_\lambda} \frac{f_{\theta,\lambda}(Y^n)}{f_{\theta^*}(Y^n)} d\pi_\lambda(\theta) \geq \int_{d(\theta,\theta^*) \leq \epsilon_{n,\lambda}} e^{\ell_n(\theta) - \ell_n(\theta^*)} d\pi_\lambda(\theta) \\ &\gtrsim e^{-c_1 n \epsilon_n^2} \pi_\lambda(d(\theta^*, \theta) \leq \epsilon_n) \\ &\lesssim e^{-c_2 n \epsilon_n^2} \pi_\lambda(d(\theta^*, \theta) \leq \epsilon_n) + e^{-nc_2 \epsilon_n^2} \end{aligned}$$

Under *stringent* conditions

$$\pi(\lambda : \epsilon_{n,\lambda} \leq M\epsilon_{n,\lambda^*} | Y^n) \rightarrow 1$$

$$\hat{\lambda} \rightarrow \{\lambda : \epsilon_{n,\lambda} \leq M\epsilon_{n,\lambda^*}\}$$

[Only useful if  $\lambda \neq \lambda^* \Rightarrow \epsilon_{n,\lambda} \gg \epsilon_{n,\lambda^*}$ ]

# NP priors $\mathfrak{M}_0$ and $\mathfrak{M}_1$

## ▶ Testing for monotonicity

$$Y = (y_1, \dots, y_n) \stackrel{iid}{\sim} f, \quad \text{or} \quad y_i = f(x_i) + \epsilon_i,$$

- Model  $\mathfrak{M}_0$  :  $f =$  decreasing
- Model  $\mathfrak{M}_1$  :  $f$  has no shape constraints.

## ▶ 1rst idea

- Prior on  $\mathfrak{M}_0$  : Mixtures of  $\mathcal{U}(0, \theta)$

$$f_P(y) = \int_0^\infty \frac{\mathbb{1}_{y \leq \theta}}{\theta} dP(\theta), \quad P \sim DP(AG)$$

- Prior on smooth densities : e.g. Mixtures of Betas

$$f_P(y) = \int_0^\infty g_{z,z/\epsilon}(y) dP(\epsilon), \quad (z, P) \sim \pi_z \times DP(AG)$$

[Bad idea]

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[Bad idea]

# 1rst solution

$$y_i \in [0, 1]$$

$$f(x) = f_{\omega,k} := \sum_{j=1}^k k\omega_j \mathbf{1}_{[(j-1)/k, j/k]}(x), \quad \sum_{j=1}^k \omega_j = 1$$

## ► Prior

$$k \sim P; \quad (\omega_1, \dots, \omega_k) \sim \pi_k, \quad \text{e.g. } \mathcal{D}(\alpha_1, \dots, \alpha_k)$$

## ► Posterior probabilities

$$\pi[\mathfrak{M}_0 | Y] = \pi \left[ \max_j (\omega_j - \omega_{j-1}) \leq 0 \mid Y \right]$$

## ► Problem : if $f \in \mathfrak{M}_0$ but has flat parts



# Result

▶ **Question** : ??  $\pi[\mathfrak{M}_0 | Y] = 1 + o_p(1)$  if  $f \in \mathfrak{M}_0$ .

▶ **Answers** : **Not always**

$$g(\delta) := \mathcal{L}eb \left( \left\{ x; \inf_{y>x} \frac{f(x) - f(y)}{y - x} \leq \delta \right\} \right)$$

• For all  $f_0$  s.t.  $g(\delta) = 0$ , if

$$P^\pi \left[ k \lesssim (n/\log n)^{1/5} \mid Y \right] = 1 + o_p(1)$$

$$P^\pi[\mathfrak{M}_0 | Y] = 1 + o_p(1) \rightarrow \text{Consistent test}$$

e.g. if  $k^3 \sim \mathcal{P}(\lambda)$ .

• For all  $f_0$  s.t.  $g(\delta) = \sqrt{\delta}$ , idem with  $k^7 \sim \mathcal{P}(\lambda)$ .

# Inconsistencies

If  $f_0$  is constant on  $[a, b] \subset (0, 1)$  and if

$$\pi(3/(b-a) < k < \sqrt{n/\log n} | Y^n) \rightarrow 1$$

then with probability greater than  $1/2$  (asymptotically)

$$\pi(\mathfrak{M}_0 | Y^n) < 1/2$$

[Inconsistency of the testing procedure]

▶ **Not satisfying** : Cannot be consistent over whole set of decreasing functions.

Increasing the set of functions by lowering  $k \Rightarrow$  leads to poor power.

▶ **Change of loss function**  $\rightarrow$  new test based on

$$P^\pi [d(f, \mathfrak{M}_1) \leq \epsilon | Y]$$

Choice of  $\epsilon$  ?

# Moving away (slightly) from the 0-1 loss function for unseparated hypotheses [JB Salomond]

## ► New loss function

$$L_{\tau}(\theta, \delta) = \begin{cases} 0 & \text{if } d(\theta, \mathfrak{M}_0) \leq \tau \\ 1 & \text{if } d(\theta, \mathfrak{M}_0) > \tau \end{cases}$$

Equivalent to testing

$$H_0 : d(\theta, \mathfrak{M}_0) \leq \tau, \quad H_1 : d(\theta, \mathfrak{M}_0) > \tau$$

## ► Bayes estimator

$$\delta^{\pi} = \begin{cases} 0 & \text{if } \pi(d(\theta, \mathfrak{M}_0) \leq \tau | Y^n) > 1/2 \\ 1 & \text{if otherwise} \end{cases}$$

# Choice of $\tau$

- If prior information on tolerance level  $\tau$  chosen a priori
- Calibration by  $\tau_n$  smallest s.t. Type I error

$$\sup_{\theta \in \mathfrak{M}_0} P_\theta [\pi(d(\theta, \mathfrak{M}_0) \leq \tau_n | Y^n) \leq 1/2] = o(1)$$

- Study of  $\rho_n$  s.t. (separation rate)

$$\sup_{\theta: d(\theta, \mathfrak{M}_0) > \rho_n} P_\theta [\pi(d(\theta, \mathfrak{M}_0) \leq \tau_n | Y^n) < 1/2] = o(1)$$

[Control of type II error over  $\rho_n$  separated hypotheses]

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- Difficult analysis in some cases : Not necessarily to determine  $\tau_n$  . e.g. in the case of testing for monotonicity – only for simple families of priors
- optimal  $\tau_n = \tau_0 v_n$  where  $v_n$  known  $\tau_0$  arbitrary. Calibration of  $\tau_0$  for finite  $n$  ?
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# Semi-parametric : $\theta = (\psi, \eta)$

$$\mathfrak{M}_1 : \psi = \psi_0, \quad \mathfrak{M}_2 : \psi \neq \psi_0$$

- Cox hazard :

$$h_\theta(x|z) = e^{\psi^t z} \eta(x), \quad \mathfrak{M}_1 : \psi = 0$$

- Long memory parameter :  $\mathfrak{M}_1 : h = 0$

$$Y \sim \mathcal{N}(0, T_n(f_\theta)), \quad f_\theta(x) = (1 - \cos x)^h \eta(x), \quad \eta > 0 \in \mathcal{C}_b$$

## ► Saved by BvM

$$\pi(v_n(\psi - \hat{\psi}) \in A | Y) \approx Pr(\mathcal{N}_d(0, 1) \in A) \Rightarrow B_{1/2} \gtrsim v_n^{-d/2} \rightarrow +\infty$$

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## The 2 - samples test

$$X^n = (X_1, \dots, X_n) \stackrel{iid}{\sim} F_X, \quad Y^n = (Y_1, \dots, Y_n) \stackrel{iid}{\sim} F_Y$$

$$H_0 : F_X = F_Y = F \quad H_1 : F_X \neq F_Y$$

- **Prior**  $H_0 : F \sim \pi$  and  $H_1 : F_X, F_Y \sim \pi$  ind.

$$B_{1/2} = \frac{m_{2n}(X^n, Y^n)}{m_n(X^n)m_n(Y^n)}, \quad \text{consistency?}$$

- **Hardly any literature (Bayesian)** on 2 - sample test
- Holmes et al. [PolyaT]
  - Dunson & Lock [ $\approx$  parametric]
  - Chen & Hansen [censored-PolyaT]

# Other ways of getting away from 0-1 loss functions

- ▶ **distance penalized losses** Robert & Rousseau, Rousseau Goodness of fit test :  $Y^n = (y_1, \dots, y_n), y_i \stackrel{iid}{\sim} f$

$$H_0 : f \in \mathcal{F}_0 = \{f_\theta, \theta \in \Theta \subset \mathbb{R}^d\}, \quad H_1 : f \notin \mathcal{F}_0$$

$$L(\theta, \delta) = \begin{cases} (d(\theta, \mathfrak{M}_0) - \epsilon) \mathbb{I}_{d(\theta, \mathfrak{M}_0) > \epsilon} & \text{when } \delta = 0 \\ (\epsilon - d(\theta, \mathfrak{M}_0)) \mathbb{I}_{d(\theta, \mathfrak{M}_0) \leq \epsilon} & \text{when } \delta = 1 \end{cases}$$

- ▶ **Bayes test**

$$\delta^\pi = 1 \quad \Leftrightarrow \quad E^\pi[d(\theta, \mathfrak{M}_0) | Y^n] > \epsilon$$

- ▶ **Calibration of  $\epsilon$  using a conditional predictive  $p$ -value**

$$p(y^n) = \int_{\Theta} P_\theta(T(Y^n) > T(y^n) | \hat{\theta}, y^n) \pi_0(\theta) d\theta$$

# Other ways

There are many other ways . . .



- Point null hypothesis : Consistency of BF  $\leftrightarrow$  consistency of the posterior under  $H_1$
- Parametric null : more involved .  $\Pi_1$  can be more favorable to  $f_{\theta_0}$  than  $\Pi_0$ .
- Nonparametric Null . e.g.  $\mathcal{F}_0 = \{f \downarrow\} \rightarrow$  need to be even more carefull
- Are BIC or BIC type formula better than BF ?

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